

Electric Cylinder Operation:

The input shaft (worm) shaft rotates a wormgear, which in turn rotates the lifting screw. As the lifting screw rotates, it forces the lifting nut (fixed to the cylinder tube) to translate, thus extending or retracting the cylinder tube. For proper operation, the load being lifted must be restrained from rotation.

Joyce offers Electric Cylinders in several models including:

- Standard
- Motor mount
- ComDRIVE®

A guide for ordering is on pages 120 and 121.

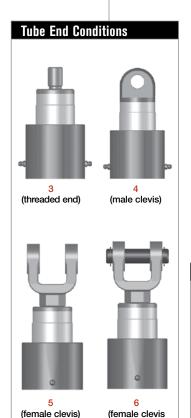
ELECTRIC CYLINDERS ORDERING INFORMATION

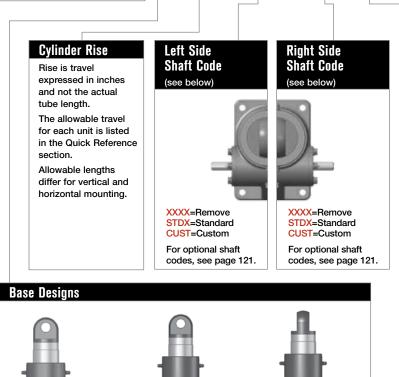
Instructions: Select a model number from this chart.

2.5-Ton	2.5-Ton	3-Ton	3-Ton	5-Ton	5-Ton	10-Ton	10-Ton	20-Ton	20-Ton
ACME Screw	Ball Screw	ACME Screw	Ball Screw	ACME Screw	Ball Screw	ACME Screw	Ball Screw	ACME Screw	Ball Screw
ECAL242.5 ECAH62.5 ECAH122.5 ECAH242.5	ECBL62.5 ECBL122.5 ECBL242.5 ECBM62.5 ECBH62.5	ECAL63 ECAL123 ECAL243	ECBL63 ECBL123 ECBL243 ECBH63 ECBH123 ECBH243	ECAL65 ECAL245 ECAM65 ECAM125 ECAM245 ECAH65 ECAH125 ECAH245	ECBL65 ECBL125 ECBL245 ECBM65 ECBM125 ECBM245 ECBH65 ECBH125 ECBH245	ECAL810 ECAL2410 ECAM810 ECAM82410 ECAH810 ECAH2410	ECBL810 ECBL2410 ECBM810 ECBM2410 ECBH810 ECBH2410	ECAL820 ECAL2420 ECAM820 ECAM82420 ECAH820 ECAH820	ECBL820 ECBL2420

Important Note: Electric Cylinders that are ≥ 30% efficient may lower under load. Brake motors or external locking systems are required. Detailed information about each electric cylinder model is available on pages 125-134.

Sample Part Number: ECAL654C-18.5-STDX-STDX-X





Additional Options*

X=Standard, no additional options

S=Additional Specification Required (comment as necessary)

Finishes p. 182 F1=Do Not Paint

F2=Epoxy Paint F3=Outdoor Paint Process

Motor Options

M1=Less Motor M2=Brake Motor M3=Single Phase Motor (120VAC)

M4=50Hz Motor M5=Special Motor

Grease/Seals
H1=High Temperature
Operation
H2=Food Grade Grease

* Specify as many options as needed

R=Rotated Clevis Base

C=Clevis Base

F=Flange Base

with pin)

ELECTRIC CYLINDERS SHAFT CODES

Instructions: Select the appropriate shaft codes for both right and left hand shafts. One shaft code must be specified for each side of the electric cylinder.

Mechanical Counters (p. 180)

CNT0=0.001" Increments

Note: Contact Joyce for availability and options.



Hand Wheels (p. 180)

HW04=4" dia HW06=6" dia HW08=8" dia HW10=10" dia HW12=12" dia



Not recommended for electric cylinders that are $\geq 30\%$ efficient.

Geared Potentiometers (p. 175)

POTA=0-10V

POTB=4-20mA



POTD=4-20mA w/2 switches

IP65 rated enclosures

Encoders (pp. 176-177)

ENCA=Absolute Encoder 0-10 VDC, programmable ENCB=Absolute Encoder 4-20mA, programmable

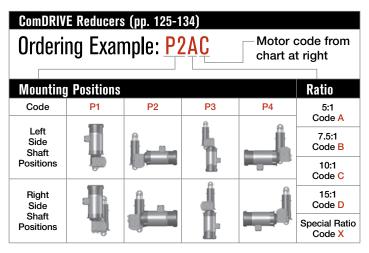
ENCC=Absolute Encoder CAN Open

ENCD=Absolute Encoder SSI

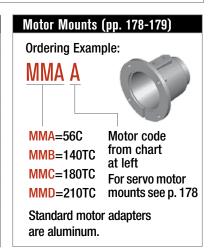
ENCS=Stainless Steel Incremental Encoder 1024 PPR

ENCX=Incremental Encoder 200 PPR

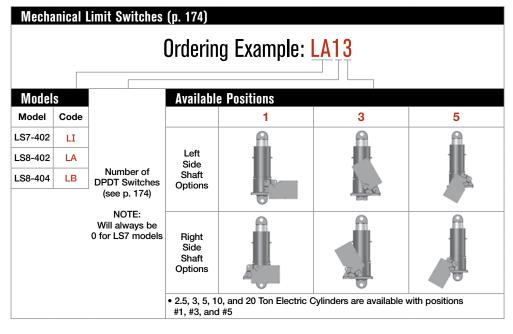
ENCY=Incremental Encoder 1024 PPR



Motors	
Size	Code
1/4 HP	K
1/3 HP	Α
1/2 HP	В
3/4 HP	С
1 HP	D
1-1/2 HP	E
2 HP	F
3 HP	L
5 HP	G



All standard motors are 3-phase, 208-230/460 VAC or 230/460 VAC. Specify the appropriate motor size from the chart above. Refer to the "Additional Options" chart on the preceding page as needed. Brake motors are required for electric cylinders that are more than 30% efficient. Contact Joyce for options that are not listed.



To order additional options, use these part numbers (p. 124)
Female Clevis Bracket
FCB-30
FCB-100
FCB-200
Clevis Pin w/ retaining rings
CP-30
CP-100
CP-200
Female Rod Clevis
FRC-30
FRC-100
FRC-200

ELECTRIC CYLINDERS MODELS



Standard

The Joyce standard electric cylinder is intended for applications where the customer provides their own drive mechanism. To determine capacity, input torque, and turns-per-inch use the specification chart on page 123. This design can also be used where one or more electric cylinders are being driven by one common drive motor or in combination with the motor mount (direct drive) or ComDRIVE® models listed below.

Example part number: ECAL635C-15.00-STDX-HW08-X

Acme screw (ECA), low lead (L), 6:1 gear ratio (6), 3-ton capacity (3), female clevis (5), clevis base (C), 15 inches rise (15), standard input shaft left hand side of jack (STDX), 8" diameter hand wheel right side of jack (HW08), no additional options (X).



Motor Mount (direct drive)

Joyce motor mount electric cylinders are intended for higher speed applications. Motor mount models can be used in conjunction with one or more of the standard electric cylinders shown above. To determine lifting speed and capacity, view "direct drive" models shown on the quick reference charts (pages 125-129). Standard motors are 3-phase, 230/460 VAC, 60 Hz, and 1750 RPM. For additional motor information, see page 179.

Example part number: ECAM24104R-9.50-STDX-MMBE-F2

Acme screw (ECA), medium lead (M), 24:1 gear ratio (24), 10-ton capacity (10), male clevis (4), rotated clevis base (R), 9 1/2 inches rise (9.50), standard input shaft left hand side of jack (STDX), 145TC motor mount (MMB) with 1 1/2 HP motor (E) on right hand side, epoxy paint (F2).



ComDRIVE®

Joyce ComDRIVE® models include a right angle gearmotor mounted to the right or left side of the standard model. ComDRIVEs are intended for applications requiring heavy lifting capacities at speeds up to 34 inches per minute (acme screw) and 104 inches per minute (ball screw). ComDRIVE models can be used in conjunction with one or more of the standard electric cylinders shown above. To determine lifting speeds and capacity, refer to the charts on pages 125-129.

Example part number: ECAH8206F-52.25-P1CL-ENCX-M3

Acme screw (ECA), high lead (H), 8:1 gear ratio (8), 20-ton capacity (20), female clevis with pin (6), flange base (F), 52 1/4 inches rise (52.25), 10:1 reducer with a 3 horsepower motor mounted to left hand side of jack (P1CL), encoder on right side of jack (ENCX), single phase motor (M3).

ELECTRIC CYLINDERS SPECIFICATIONS

Model	Static Capacity	Screw Diameter	Thread Pitch/Lead	Wormgear Ratio	Worm Shaft Turns for 1" Travel	Tare Torque (Inch Lbs.)	Starting Torque (Inch Lbs.)	Operating Torque (Inch Lbs.)	Translating Tube Torque (Inch Lbs.)	Base Weight	Weight per Inch Travel
ECAL242.5			.25 pitch ACME 2C	24:1	96	6	.018W*	.010W* @500 RPM	.098W*		
ECAH62.5			QE nitah	6:1	12	8	.056W*	.040W* @500 RPM		24	1.5
ECAH122.5			.25 pitch .5 lead ACME 2C	12:1	24	7	.035W*	.023W* @500 RPM	.140W*	24	1.3
ECAH242.5			10 1044 7101112 20	24:1	48	6	.025W*	.014W* @500 RPM			
ECBL62.5	2.5 ton	1		6:1	24	8	.017W*	.013W* @500 RPM			
ECBL122.5			0.25 lead ball	12:1	48	7	.010W*	.008W* @500 RPM	.045W*		
ECBL242.5				24:1	96	6	.008W*	.005W* @500 RPM		30	1.5
ECBM62.5			.5 lead ball	6:1	12	8	.033W*	.026W* @500 RPM	.089W*		
ECBH62.5			1.0 lead ball	6:1	6	8	.065W*	.051W* @500 RPM	.177W*		
ECAL63				6:1	24	9	.048W*	.033W* @500 RPM			
ECAL123		1 1/4	.25 pitch ACME 2C	12:1	48	8	.030W*	.018W* @500 RPM	.114W*	26	1.9
ECAL243				24:1	96	7	.021W*	.011W* @500 RPM			
ECBL63				6:1	30	9	.013W*	.011W* @500 RPM			
ECBL123	3 ton	1 3/20	.2 lead ball	12:1	60	8	.008W*	.006W* @500 RPM	.036W*		1.9
ECBL243				24:1	120	7	.006W*	.004W* @500 RPM		32	
ECBH63				6:1	9.6	9	.041W*	.032W* @500 RPM		02	
ECBH123		1 1/16	.625 lead ball	12:1	19.2	8	.025W*	.018W* @500 RPM	.111W*		1.8
ECBH243				24:1	38.4	7	.018W*	.011W* @500 RPM			
ECAL65			.25 pitch ACME 2C	6:1	24	15	.057W*	.039W* @300 RPM	.130W*		
ECAL245			.20 piton AoME 20	24:1	96	12	.026W*	.014W* @300 RPM	.10044		
ECAM65				6:1	16	15	.065W*	.045W* @300 RPM			
ECAM125			.375 pitch STUB ACME	12:1	32	13	.041W*	.025W* @300 RPM	.151W*	50	2.3
ECAM245				24:1	64	12	.030W*	.016W* @300 RPM		30	2.0
ECAH65			OF nitab F load	6:1	12	15	.073W*	.051W* @300 RPM			
ECAH125			.25 pitch .5 lead ACME 2C	12:1	24	13	.046W*	.029W* @300 RPM	.171W*		
ECAH245			AOME EO	24:1	48	12	.033W*	.018W* @300 RPM			
ECBL65	5 ton	1 1/2	.474 lead ball	6:1	12.66	15	.032W*	.025W* @300 RPM	004144		
ECBL125				12:1	25.33	13	.020W*	.014W* @300 RPM	.084W*		
ECBL245				24:1	50.66	12	.015W*	.009W* @300 RPM			
ECBM65				6:1	6	15	.067W*	.052W* @300 RPM			
ECBM125			1.0 lead ball	12:1	12	13	.042W*	.030W* @300 RPM	.177W*	65	2.3
ECBM245				24:1	24	12	.031W*	.018W* @300 RPM			
ECBH65				6:1	3.2	15	.125W*	.098W* @300 RPM			
ECBH125			1.875 lead ball	12:1	6.4	13	.079W*	.055W* @300 RPM	.332W*		
ECBH245				24:1	12.8	12	.057W*	.034W* @300 RPM			
ECAL810			.25 pitch ACME 2C	8:1	32	30	.052W*	.036W* @200 RPM	.162W*		2.8
ECAL2410			.20 piton Admit 20	24:1	96	25	.026W*	.016W* @200 RPM	.10244		2.0
ECAM810		2	.5 pitch ACME 2C	8:1	16	30	.061W*	.044W* @200 RPM	.195W*	64	2.6
ECAM2410		_	.o piton AoME 20	24:1	48	25	.031W*	.019W* @200 RPM	.10044	04	2.0
ECAH810			.333 pitch .666 lead	8:1	12	30	.070W*	.051W* @200 RPM	.228W*		2.7
ECAH2410	10 ton		ACME 2C	24:1	36	25	.035W*	.022W* @200 RPM			
ECBL810	10 (011		.474 lead ball	8:1	16.88	30	.023W*	.019W* @200 RPM	.084W*		
ECBL2410				24:1	50.66	25	.012W*	.008W* @200 RPM	.00111		
ECBM810		1 1/2	1.0 lead ball	8:1	8	30	.049W*	.040W* @200 RPM	.172W*	81	2.3
ECBM2410			1.0 road ball	24:1	24	25	.024W*	.017W* @200 RPM	2**	"	
ECBH810			1.875 lead ball	8:1	4.27	30	.091W*	.074W* @200 RPM	.332W*		
ECBH2410			1.010 load ball	24:1	12.8	25	.045W*	.031W* @200 RPM	.00211		
ECAL820			.25 pitch ACME 2C	8:1	32	60	.066W*	.044W* @200 RPM	.194W*		4.9
ECAL2420			20 piton Admit 20	24:1	96	40	.035W*	.019W* @200 RPM	.1011		0
ECAM820		2 1/2	.5 pitch ACME 2C	8:1	16	60	.075W*	.052W* @200 RPM	.227W*	124	4.7
ECAM2420	20 ton	2 1/2	TO PITOTI MOINE ZO	24:1	48	40	.039W*	.022W* @200 RPM	.221 VV	124	7.1
ECAH820	20 (011		.375 pitch .75 lead	8:1	10.67	60	.088W*	.062W* @200 RPM	.273W*		4.8
ECAH2420			ACME 2C	24:1	32	40	.046W*	.027W* @200 RPM	.21000		4.0
ECBL820		2 1/4	.5 lead ball	8:1	16	60	.026W*	.020W* @200 RPM	.089W*	164	4.5
ECBL2420		2 1/4	.o icau bali	24:1	48	40	.014W*	.009W* @200 RPM	.ooavv	107	4.0

Important Note: Electric cylinders that are ≥ 30% are not self-locking. Brake motors or external locking systems are required.

*W: Load in pounds

Tare Torque: Initial torque to overcome seal and normal assembly drag. This value must be added to starting torque or operating torque values.

Starting Torque: Torque value required to start moving a given load (dissipates to operating torque values once the load begins moving).

Operating Torque: Torque required to continuously raise a given load at the input RPM listed.

Translating Tube Torque: Torque required to resist tube rotation.

Lead: The distance traveled axially in one rotation of the lifting screw.

Pitch: The distance from a point on a screw thread to a corresponding point on the next thread, measured axially.

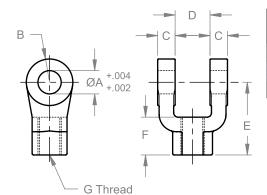
Note: This chart is provided for reference only. For specific information such as allowable continuous travel or ball nut life and other performance factors refer to JAX® Online software or contact Joyce.

ELECTRIC CYLINDERS CLEVIS AND BRACKET

Female Rod Clevis

A female rod clevis end is included for type 5 and type 6 end conditions.

They are also available as options.

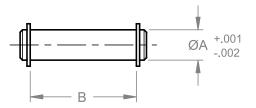


Cylinder	Part	Dimensions (Inches)								
Capacity	Number	ØA	В	C	D	E	F	G	Capacity (Lbs.)	
2.5 & 3	FRC-30	3/4	3/4	5/8	1 1/4	2 3/8	1 1/8	3/4-16	11,200	
5 & 10	FRC-100	1	1	3/4	1 1/2	3 1/8	1 5/8	1-14	19,500	
20	FRC-200	1 3/8	1 3/8	1	2	4 1/8	2	1 1/4-12	33,500	

Clevis Pin with Retaining Rings

A clevis pin with retaining rings is included on type 6 end conditions.

They are also available as options.

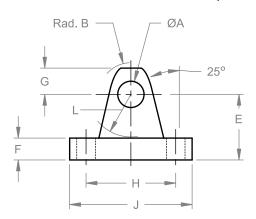


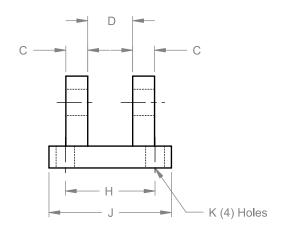


Cylinder	Part	Dimension	Load Capacity	
Cylinder Capacity	Number	ØA B		(Lbs.)
2.5 & 3	CP-30	3/4	2 5/8	19,300
5 & 10	CP-100	1	3 1/8	34,300
20	CP-200	1 3/8	4 1/8	65,000

Female Clevis Bracket

Female clevis brackets are available as options.





Cylinder	Part	Dimensions (Inches)										Load	
Capacity	Number	ØA	В	C	D	E	F	G	Н	J	K	L	Capacity (Lbs.)
2.5 & 3	FCB-30	3/4	29/32	5/8	1 1/4	1 7/8	5/8	3/4	3.82	5	17/32	1 3/16	14,000
5 & 10	FCB-100	1	1 1/4	3/4	1 1/2	2 1/4	3/4	1	4.95	6 1/2	21/32	1 1/2	19,200
20	FCB-200	1 3/8	1 21/32	1	2	3	7/8	1 3/8	5.73	7 1/2	21/32	2	33,500

Use the following charts to select the electric cylinder that best fits your application. Refer to drawings on page 130. Contact Joyce with questions regarding the proper selection of electric cylinders.

2.5-Ton Thr	ust Capacity E	Electric Cylin	ders								
Model	Max Static Capacity	Screw Lead	Linear Speed	External Gearbox	Estimated			Max Dynamic L	oad at HP (lbs)		
Model	(tons)	(in)	(in/min)	Ratio	Efficiency	.33НР	.5HP	.75HP	1HP	1.5HP	2HP
ACME Screw											
ECAL242.5	2.5	0.250	1.76	10	14%	5,000					
ECAL242.5	2.5	0.250	2.38	7.5	15%	5,000					
ECAH242.5	2.5	0.500	3.53	10	20%	5,000					
ECAH242.5	2.5	0.500	4.76	7.5	21%	5,000					
ECAH122.5	2.5	0.500	7.06	10	25%	4,234	5,000				
ECAH122.5	2.5	0.500	9.52	7.5	26%	3,219	5,000				
ECAH62.5	2.5	0.500	14.12	10	28%	2,374	3,701	5,000			
ECAL242.5	2.5	0.250	18.23	Direct drive	21%	756	1,543				
ECAH62.5	2.5	0.500	19.04	7.5	29%	1,787	2,811	4,317			
ECAH62.5	2.5	0.500	27.78	5	30%	1,213	1,946	3,025			
ECAH242.5	2.5	0.500	36.46	Direct drive	30%	525	1,072				
ECAH122.5	2.5	0.500	72.92	Direct drive	33%		555	1,010	1,464	2,373	
ECAH62.5	2.5	0.500	145.83	Direct drive	36%			512	754	1,238	1,723
Ball Screw											
ECBL242.5	2.5	0.250	1.76	10	30%	5,000					
ECBL242.5	2.5	0.250	2.38	7.5	32%	5,000					
ECBL122.5	2.5	0.250	3.53	10	38%	5,000					
ECBL122.5	2.5	0.250	4.76	7.5	40%	5,000					
ECBL62.5	2.5	0.250	7.06	10	43%	5,000					
ECBL62.5	2.5	0.250	9.52	7.5	45%	5,000					
ECBL62.5	2.5	0.250	13.89	5	47%	3,752	5,000				
ECBL242.5	2.5	0.250	18.23	Direct drive	46%	1,624	3,315				
ECBM62.5	2.5	0.500	19.04	7.5	45%	2,763	4,347	5,000			
ECBM62.5	2.5	0.500	27.78	5	47%	1,876	3,010	4,678	5,000		
ECBL122.5	2.5	0.250	36.46	Direct drive	52%	762	1,718	3,123	4,528	5,000	
ECBH62.5	2.5	1.000	38.08	7.5	45%	1,381	2,173	3,338			
ECBH62.5	2.5	1.000	55.56	5	47%	938	1,505	2,339	3,247		
ECBL62.5	2.5	0.250	72.92	Direct drive	55%		833	1,582	2,331	3,830	5,000
ECBM62.5	2.5	0.500	145.83	Direct drive	55%			791	1,166	1,915	2,664
ECBH62.5	2.5	1.000	291.67	Direct drive	55%				583	957	1,332

2.5-Ton Electric Cylinders			
	Maximo	um Rise	Cylinder Tube Torque
	Vertical Operation	Horizontal Operation	(in*lb) Per Pound Thrust
ACME Screw			
ECAL	28"	21"	.098
ECAH	28"	21"	.139
Ball Screw			
ECBL	41"	31"	.045
ECBM	44"	33"	.089
ECBH	41"	31"	.178

Selection Guidelines:

- Select the model most closely matching your desired load and speed requirements. The chart is sorted by static capacity, then screw type (ACME or ball), then travel speed.
- To determine the maximum rise for the model selected, see maximum rise chart above.
- L, M, and H in the model numbers designate low, medium, or high screw leads.
- ECA models are not suitable for duty cycles greater than 25%.
- All models with efficiencies >30% require a brake motor.
- Models with efficiencies ≤30% are self-locking in the absence of vibration. A brake motor is required if vibration is present or faster stopping times are desired.

- Loads and speeds shown assume use of a 1750 rpm 3ph AC induction motor.
- Cylinder tube torque per pound thrust is the means to calculate how much torque must be resisted at the mounting locations of the cylinder. To calculate torque (in*lb), multiply the value in the chart times the load in pounds.
- When ordering cylinders with a ComDRIVE reducer the listed part number should specify the proper 4 letter ComDRIVE shaft code from page 121. Units with a "direct drive" listing should specify the proper 4 letter motor mount code listed on page 121.
- Note: For normal operation, the translating tube end must be restrained from rotation.

Use the following charts to select the electric cylinder that best fits your application. Refer to drawings on page 131. Contact Joyce with questions regarding the proper selection of electric cylinders.

3-Ton Thrus	t Capacity Ele	ectric Cylinde	ers								
Model	Max Static Capacity	Screw Lead	Linear Speed	External Gearbox	Estimated			Max Dynamic L	oad at HP (lbs)		
Wiouci	(tons)	(in)	(in/min)	Ratio	Efficiency	.33НР	.5HP	.75HP	1HP	1.5HP	2HP
ACME Screw											
ECAL243	3	0.250	1.76	10	12%	6,000					
ECAL243	3	0.250	2.38	7.5	13%	6,000					
ECAL123	3	0.250	3.53	10	15%	5,183	6,000				
ECAL123	3	0.250	4.76	7.5	16%	3,926	6,000				
ECAL63	3	0.250	7.06	10	17%	2,906	4,547	6,000			
ECAL63	3	0.250	9.52	7.5	18%	2,179	3,446	5,310			
ECAL63	3	0.250	13.89	5	19%	1,468	2,375	3,710	5,162		
ECAL243	3	0.250	18.23	Direct drive	18%		1,215				
ECAL63	3	0.250	72.92	Direct drive	22%				899	1,499	2,098
Ball Screw											
ECBL243	3	0.200	1.41	10	30%	6,000					
ECBL243	3	0.200	1.90	7.5	32%	6,000					
ECBL123	3	0.200	2.82	10	38%	6,000					
ECBL123	3	0.200	3.81	7.5	40%	6,000					
ECBH243	3	0.625	4.41	10	30%	6,000					
ECBL63	3	0.200	5.65	10	43%	6,000					
ECBH243	3	0.625	5.95	7.5	32%	6,000					
ECBL63	3	0.200	7.62	7.5	45%	6,000					
ECBH123	3	0.625	8.82	10	38%	5,183	6,000				
ECBL63	3	0.200	11.11	5	47%	4,587	6,000				
ECBH123	3	0.625	11.90	7.5	40%	3,926	6,000				
ECBL243	3	0.200	14.58	Direct drive	46%	1,686	3,798				
ECBH63	3	0.625	17.65	10	43%	2,906	4,547	6,000			
ECBH63	3	0.625	23.80	7.5	45%	2,179	3,446	5,310			
ECBL123	3	0.200	29.17	Direct drive	52%	758	1,952	3,709	5,465	6,000	
ECBH63	3	0.625	34.72	5	47%	1,468	2,375	3,710	5,162		
ECBH243	3	0.625	45.57	Direct drive	46%		1,215				
ECBL63	3	0.200	58.33	Direct drive	55%		937	1,874	2,810	4,683	6,000
ECBH123	3	0.625	91.15	Direct drive	52%		625	1,187	1,749	2,873	
ECBH63	3	0.625	182.29	Direct drive	55%				899	1,499	2,098

3-Ton Electric Cylinders			
	Maxim	um Rise	Cylinder Tube Torque
	Vertical Operation	Horizontal Operation	(in*lb) Per Pound Thrust
ACME Screw			
ECAL	48"	36"	.113
Ball Screw			
ECBL	56"	42"	.036
ECBH	46"	34"	.111

Selection Guidelines:

- Select the model most closely matching your desired load and speed requirements. The charts are sorted by static capacity, then screw type (ACME or ball), then travel speed.
- To determine the maximum rise for the model selected, see maximum rise charts above and to the right.
- L, M, and H in the model numbers designate low, medium, or high screw leads.
- ECA models are not suitable for duty cycles greater than 25%.
- All models with efficiencies >30% require a brake motor.
- Models with efficiencies ≤30% are self-locking in the absence of vibration. A brake motor is required if vibration is present or faster stopping times are desired.

- Loads and speeds shown assume use of a 1750 rpm 3ph AC induction motor.
- Cylinder tube torque per pound thrust is the means to calculate how much torque must be resisted at the mounting locations of the cylinder. To calculate torque (in*lb), multiply the value in the chart times the load in pounds.
- When ordering cylinders with a ComDRIVE the reducer listed in the part number should specify the proper ComDRIVE 4 letter shaft code from page 121. Units with a "direct drive" listing should specify the proper 4 letter motor mount code listed on page 121.
- Note: For normal operation, the translating tube end must be restrained from rotation.

Use the following charts to select the electric cylinder that best fits your application. Refer to drawings on page 132. Contact Joyce with questions regarding the proper selection of electric cylinders.

	Max Static	Screw	Linear	External	Estimated			Max Dy	namic Load at	HP (lbs)		
Model	Capacity (tons)	Lead (in)	Speed (in/min)	Gearbox Ratio	Efficiency	.33НР	.5HP	.75HP	1HP	1.5HP	2HP	ЗНР
ACME Screv	/											
ECAL245	5	0.250	1.76	10	11%	6,895	10,000					
ECAM245	5	0.375	2.65	10	14%	5,891	9,330	10,000				
ECAH245	5	0.500	3.53	10	16%	5,193	8,224	10,000				
ECAM125	5	0.375	5.29	10	17%	3,661	5,822	9,000	10,000			
ECAH125	5	0.500	7.06	10	20%	3,227	5,132	7,933	10,000			
ECAM65	5	0.375	10.59	10	19%	2,031	3,257	5,059	7,022			
ECAH65	5	0.500	14.12	10	23%	1,790	2,871	4,460	6,189			
ECAL245	5	0.250	18.23	Direct drive	16%			1,471				
ECAM65	5	0.375	20.83	5	21%		1,634	2,635	3,723	5,768	7,813	
ECAM245	5	0.375	27.34	Direct drive	21%			1,257				
ECAH65	5	0.500	27.78	5	25%		1,441	2,322	3,282	5,085	6,887	
ECAH245	5	0.500	36.46	Direct drive	24%			1,108				
ECAM125	5	0.375	54.69	Direct drive	23%				1,085	1,935		
ECAL65	5	0.250	72.92	Direct drive	19%					1,144	1,672	2,728
ECAM65	5	0.375	109.38	Direct drive	25%						1,429	2,331
ECAH65	5	0.500	145.83	Direct drive	29%						1,259	2,055
Ball Screw												
ECBL245	5	0.474	3.34	10	30%	10,000						
ECBL125	5	0.474	6.69	10	38%	6,441	10,000					
ECBM245	5	1.000	7.06	10	30%	4,910	7,775	10,000				
ECBH245	5	1.875	13.24	10	30%	2,618	4,147	6,394				
ECBL65	5	0.474	13.37	10	43%	3,572	5,729	8,900	10.000			
ECBM125	5	1.000	14.12	10	38%	3,051	4,852	7,500	10,000			
ECBH125	5	1.875	26.47	10	38%	1,627	2,588	4,000	5,537			
ECBL65	5	0.474	26.32	5	47%	1,678	2,875	4,635	6,550	10,000		
ECBM65	5	1.000	28.23	10	43%	1,692	2,714	4,216	5,851	,,,,,,,		
ECBL245	5	0.474	34.54	Direct drive	46%	.,	_,	2,211	5,551			
ECBH65	5	1.875	52.94	10	43%		1,447	2,249	3,121			
ECBM65	5	1.000	55.56	5	47%		1,362	2,196	3,103	4,807	6,511	
ECBL125	5	0.474	69.08	Direct drive	52%		.,	1,162	1,910	3,404	4,898	
ECBM245	5	1.000	72.92	Direct drive	46%			1,048	.,	-,	.,	
ECBH65	5	1.875	104.17	5	47%			1,171	1,655	2,564	3,473	
ECBL65	5	0.474	138.16	Direct drive	55%			.,	.,000	1,720	2,513	4,101
ECBM125	5	1.000	145.83	Direct drive	52%					1,612	2,320	.,101
ECBH125	5	1.875	273.44	Direct drive	52%					1,512	1,237	
ECBM65	5	1.000	291.67	Direct drive	55%						1,191	1,942
ECBH65	5	1.875	546.88	Direct drive	55%						1,101	1,036

5-Ton Electric Cylinders							
	Maximo	Cylinder Tube Torque					
	Vertical Operation	(in*lb) Per Pound Thrust					
ACME Screw							
ECAL	59"	44"	.131				
ECAM	63"	47"	.151				
ECAH	59"	44"	.171				
Ball Screw							
ECBL	54"	40"	.084				
ECBM	54"	40"	.178				
ECBH	59"	44"	.332				

 $\textbf{Note:} \ \ \text{For proper model selection refer to Selection Guidelines on page 126}.$

Use the following charts to select the electric cylinder that best fits your application. Refer to drawings on page 133. Contact Joyce with questions regarding the proper selection of electric cylinders.

10-Ton Th	rust Capaci	ty Electric	Cylinders										
	Max	Screw	Linear	External		Max Dynamic Load at HP (lbs)							
Model	Static Capacity (tons)	Lead (in)	Speed (in/min)	Gearbox Ratio	Estimated Efficiency	.33НР	.5HP	.75HP	1HP	1.5HP	2HP	ЗНР	5HP
ACME Scre													
ECAL2410	10	0.250	1.76	10	10%	5,417	9,111	14,543	19,976				
ECAL2410	10	0.250	1.71	10	10%							20,000	
ECAM2410	10	0.500	3.53	10	16%	4,468	7,515	11,996	16,872				
ECAM2410	10	0.500	3.42	10	17%							20,000	
ECAH2410	10	0.666	4.70	10	18%	3,811	6,409	10,231	14,390				
ECAH2410	10	0.666	4.55	10	19%	0.104	0.000		0.400			20,000	
ECAL810	10	0.250	5.29	10	12%	2,134	3,689	5,977	8,468				
ECAL810	10	0.250	5.13	10	13%		0.554	0.110	0.000	44400	40.055	20,000	
ECAM2410	10	0.500	6.94	5	18%		3,554	6,112	8,896	14,126	19,355	00.000	
ECAM2410	10	0.500	7.29	5	19%		0.004	F 040	7.507	10.047	10.500	20,000	
ECAH2410	10	0.666	9.25	5	20%		3,031	5,213	7,587	12,047	16,508	00.000	
ECAH2410	10	0.666	9.71	5	21%		0.040	4 000	0.004			20,000	
ECAM810	10	0.500	10.59	10	20%		3,043	4,930	6,984			00.000	
ECAM810	10	0.500	10.25 14.10	10 10	21% 23%		0.505	4 005	E 0E7			20,000	
ECAH810 ECAH810	10 10	0.666 0.666	14.10	10	24%		2,595	4,205	5,957			20,000	
ECAL2410	10	0.000	18.23	Direct drive	14%					2,440		20,000	
ECAL2410 ECAM810	10	0.200	20.83	5	22%			2,367	3,503	5,637	7,771		
ECAM810	10	0.500	21.88	5	23%			2,307	3,303	3,037	1,111	11,611	19,837
ECAMOTO ECAH810	10	0.666	27.75	5	25%			2,019	2,988	4,808	6,628	11,011	18,037
ECAH810	10	0.666	29.14	5	26%			2,015	2,500	4,000	0,020	9.903	16.919
ECAM2410	10	0.500	36.46	Direct drive	23%					2,012		5,503	10,515
ECAL810	10	0.250	54.69	Direct drive	16%					2,012		2,461	4,732
ECAM810	10	0.500	109.38	Direct drive	26%							2,030	3,903
ECAH810	10	0.666	145.69	Direct drive	29%							2,000	3,329
Ball Screw	10	0.000	1 10.00	Direct drive	2070								0,020
ECBL2410	10	0.474	3.34	10	34%	10.130	17,038	20.000					
ECBL2410	10	0.474	6.58	5	39%	4,113	8,057	13,858	20,000				
ECBM2410	10	1.000	7.06	10	34%	4,798	8,071	12,883	18,121				
ECBM2410	10	1.000	6.83	10	36%	,		<u> </u>				20,000	
ECBL810	10	0.474	10.03	10	43%	3,990	6,899	11,178	15,834			ĺ	
ECBL810	10	0.474	9.71	10	46%							20,000	
ECBH2410	10	1.875	13.24	10	34%	2,559	4,304	6,871	9,664				
ECBM2410	10	1.000	13.89	5	39%		3,817	6,565	9,554	15,171	20,000		
ECBL810	10	0.474	19.74	5	47%		2,999	5,366	7,942	12,781	17,619		
ECBL810	10	0.474	19.11	5	50%							20,000	
ECBM810	10	1.000	21.18	10	43%		3,268	5,295	7,501				
ECBM810	10	1.000	20.50	10	46%							20,000	
ECBH2410	10	1.875	26.04	5	39%		2,036	3,501	5,096	8,091	11,086		
ECBL2410	10	0.474	34.54	Direct drive	49%					4,562			
ECBH810	10	1.875	39.71	10	43%			2,824	4,000				
ECBM810	10	1.000	41.67	5	47%			2,542	3,762	6,054	8,346		
ECBM810	10	1.000	43.75	5	49%							12,470	20,000
ECBM2410	10	1.000	72.92	Direct drive	49%					2,161			
ECBH810	10	1.875	78.13	5	47%				2,006	3,229	4,451		
ECBH810	10	1.875	82.03	5	49%						0.470	6,651	11,363
ECBL810	10	0.474	103.62	Direct drive	56%						2,478	4,602	8,849
ECBM810	10	1.000	218.75	Direct drive	56%							2,180	4,192
ECBH810	10	1.875	409.84	Direct drive	56%								2,236

10-Ton Electric Cylinders							
	Maximo	Cylinder Tube Torque					
	Vertical Operation	(in*lb) Per Pound Thrust					
ACME Screw							
ECAL	84"	63"	.161				
ECAM	60"	45"	.195				
ECAH	76"	57"	.228				
Ball Screw							
ECBL	38"	28"	.084				
ECBM	38"	28"	.178				
ECBH	41"	31"	.332				

Note: For proper model selection refer to Selection Guidelines on page 129.

Use the following charts to select the electric cylinder that best fits your application. Refer to drawings on page 134. Contact Joyce with questions regarding the proper selection of electric cylinders.

	Max	Screw	Linear	External		Max Dynamic Load at HP (lbs)							
Model	Model State Lead Cheed Coarboy Lat	Estimated Efficiency	.33НР	.5HP	.75HP	1HP	1.5HP	2HP	ЗНР	5HP			
ACME Screv	V												
ECAL2420	20	0.250	1.76	10	8%		6,459	10,813	15,552				
ECAL2420	20	0.250	1.71	10	8%							40,000	
ECAM2420	20	0.500	3.53	10	13%		5,484	9,181	13,205				
ECAM2420	20	0.500	3.42	10	14%							40,000	
ECAH2420	20	0.750	5.29	10	16%		4,560	7,634	10,979			·	
ECAH2420	20	0.750	5.13	10	17%							38,366	
ECAM2420	20	0.500	6.94	5	15%			4,305	6,621	10,972	15,324		
ECAM2420	20	0.500	7.29	5	15%							23,176	39,948
ECAM820	20	0.500	10.59	10	17%				5,276			,	
ECAM820	20	0.500	10.25	10	18%							19,447	
ECAH820	20	0.750	15.38	10	22%				4,387			,	
ECAH820	20	0.750	14.89	10	23%							16,170	
ECAL2420	20	0.250	18.23	Direct drive	11%							4,701	9,678
ECAM820	20	0.500	20.83	5	19%					4,127	5,935		
ECAM820	20	0.500	21.88	5	19%						,	9,218	16,187
ECAH820	20	0.750	31.25	5	23%						4,935		
ECAH820	20	0.750	32.81	5	24%						,	7,665	13,459
Ball Screw													
ECBL2420	20	0.500	3.53	10	33%	7,425	13,710	22,953	33,012				
ECBL2420	20	0.500	3.42	10	35%							40,000	
ECBL2420	20	0.500	6.94	5	37%		5,442	10,763	16,553	27,431	38,309		
ECBL2420	20	0.500	7.29	5	39%							40,000	
ECBL820	20	0.500	10.59	10	43%		4,876	8,857	13,189				
ECBL820	20	0.500	10.25	10	45%							40,000	
ECBL820	20	0.500	20.83	5	47%				5,797	10,317	14,837		
ECBL820	20	0.500	21.88	5	48%							23,046	40,000
ECBL2420	20	0.500	36.46	Direct drive	49%						4,697		
ECBL820	20	0.500	109.38	Direct drive	55%						,		6.665

20-Ton Electric Cylinders								
	Maximo	Cylinder Tube Torque						
	Vertical Operation	Horizontal Operation	(in*lb) Per Pound Thrust					
ACME Screw								
ECAL	100"	75"	.178					
ECAM	78"	58"	.210					
ECAH	88"	66"	.244					
Ball Screw								
ECBL	72"	54"	.089					

Selection Guidelines:

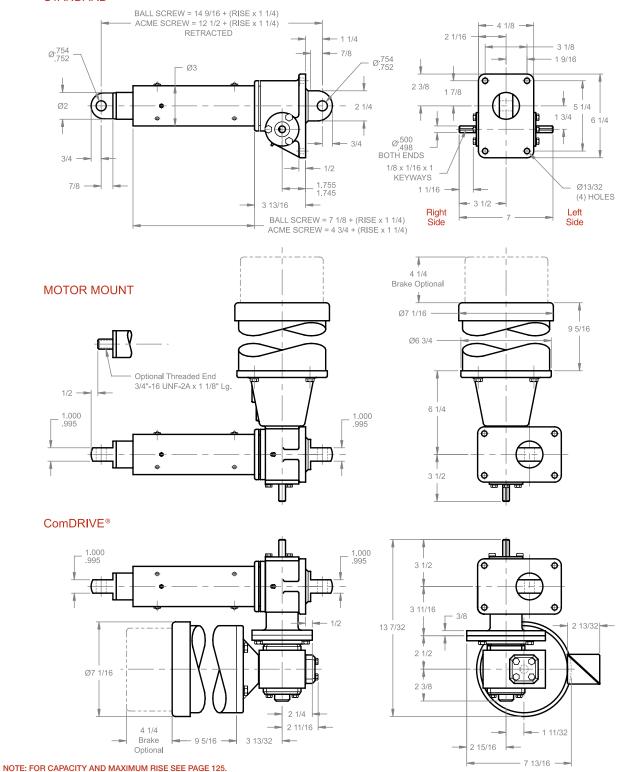
- Select the model most closely matching your desired load and speed requirements. The charts are sorted by static capacity, then screw type (ACME or ball), then travel speed.
- To determine the maximum rise for the model selected, see maximum rise charts above and to the left.
- L, M, and H in the model numbers designate low, medium, or high screw leads.
- ECA models are not suitable for duty cycles greater than 25%.
- All models with efficiencies >30% require a brake motor.
- Models with efficiencies ≤30% are self-locking in the absence of vibration. A brake motor is required if vibration is present or faster stopping times are desired.

- Loads and speeds shown assume use of a 1750 rpm 3ph AC induction motor.
- Cylinder tube torque per pound thrust is the means to calculate how much torque must be resisted at the mounting locations of the cylinder. To calculate torque (in*lb), multiply the value in the chart times the load in pounds.
- When ordering cylinders with a ComDRIVE the reducer listed in the part number should specify the proper 4 letter ComDRIVE shaft code from page 121. Units with a "direct drive" listing should specify the proper 4 letter motor mount code listed on page 121.
- Note: For normal operation, the translating tube end must be restrained from rotation.

2 1/2 TON ELECTRIC CYLINDER

ECA (ACME SCREW) ECB (BALL SCREW)

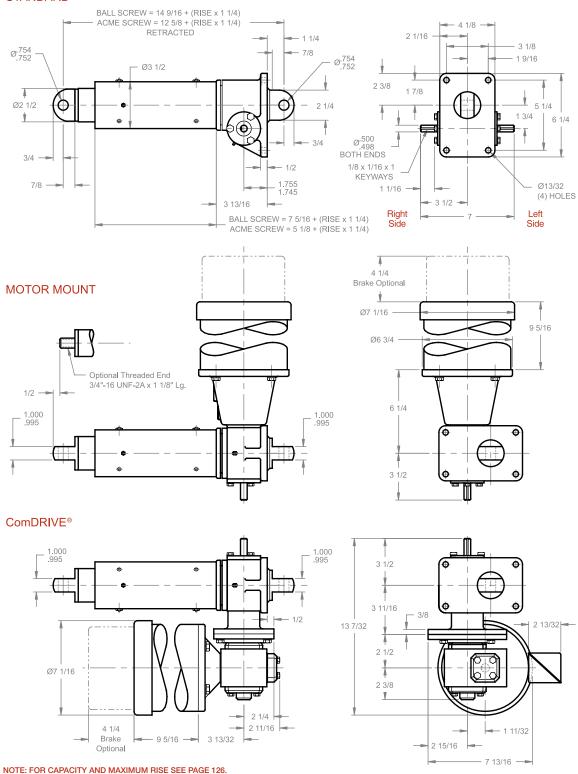
STANDARD



3 TON ELECTRIC CYLINDER

ECA (ACME SCREW) ECB (BALL SCREW)

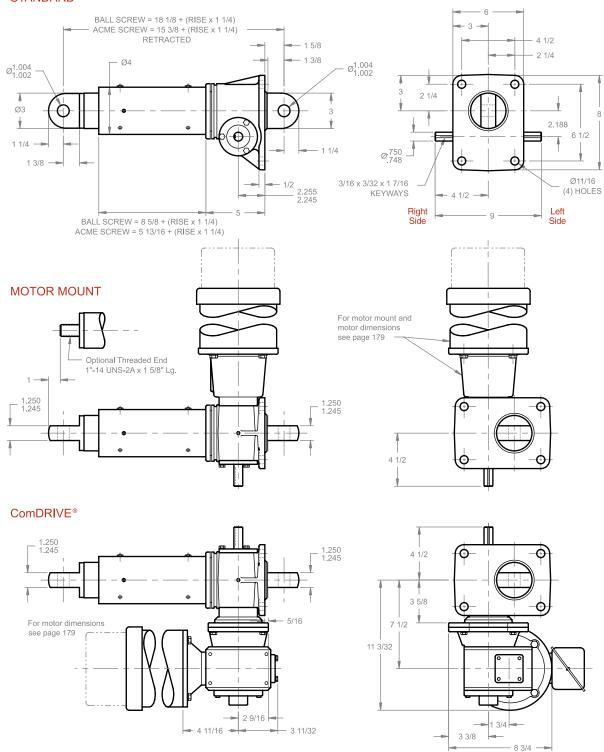
STANDARD



5 TON ELECTRIC CYLINDER

ECA (ACME SCREW) ECB (BALL SCREW)

STANDARD



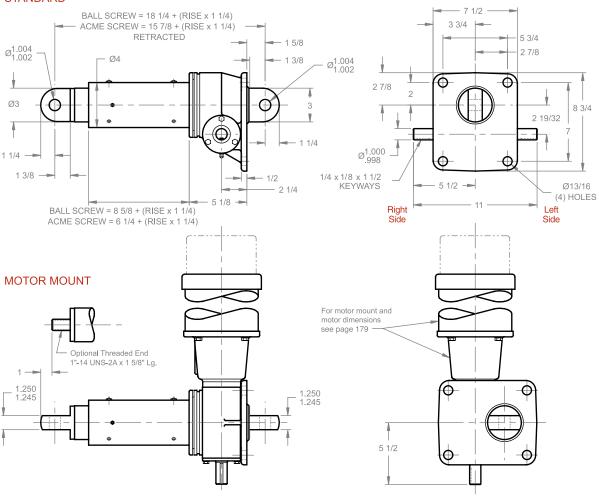
Note: Drawings are artist's conception — not for certification; dimensions are subject to change without notice.

NOTE: FOR CAPACITY AND MAXIMUM RISE SEE PAGE 127.

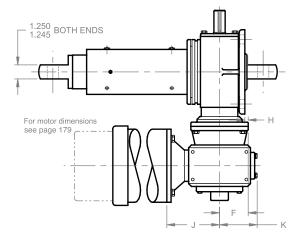
10 TON ELECTRIC CYLINDER

ECA (ACME SCREW) ECB (BALL SCREW)

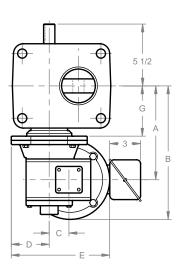




ComDRIVE®



REDUCER DIMENSIONS						
HP	1, 1 1/2, 2	3, 5				
Α	8 11/32	8 29/32				
В	11 21/32	13 17/32				
С	1 3/4	2 5/8				
D	3 3/8	4 7/16				
Е	8 7/16	11 11/16				
F	2 3/4	3 7/8				
G	4 15/32	4 15/32				
Н	0	1 1/8				
J	4 11/16	5 3/4				
K	3 11/32	4 5/16				

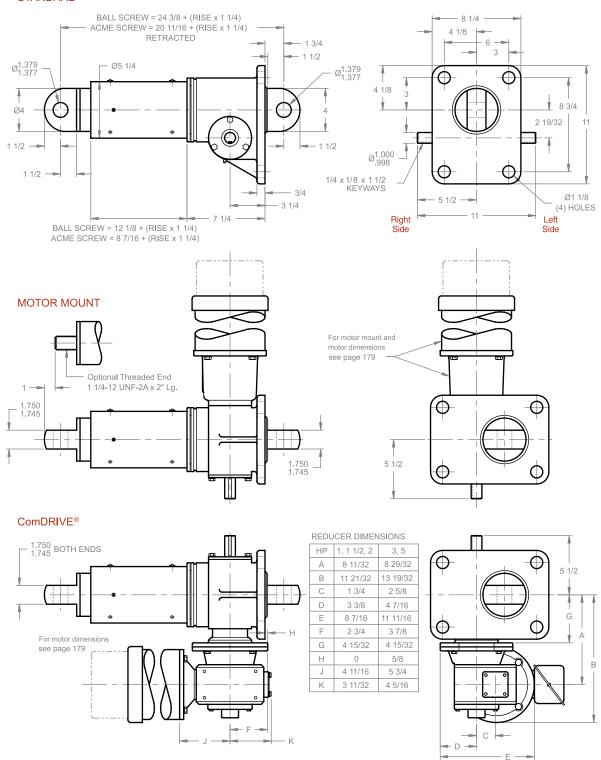


NOTE: FOR CAPACITY AND MAXIMUM RISE SEE PAGE 128.

20 TON ELECTRIC CYLINDER

ECA (ACME SCREW) ECB (BALL SCREW)

STANDARD



NOTE: FOR CAPACITY AND MAXIMUM RISE SEE PAGE 129.

 $Note: Drawings \ are \ artist's \ conception - not \ for \ certification; \ dimensions \ are \ subject \ to \ change \ without \ notice.$